

## Grupo 3 2019 - Feature #670

### 1.5 verificar agarre del robot respecto a la lata

08/27/2019 09:23 AM - José Diaz

<b>Status:</b>	New	<b>Start date:</b>	08/22/2019
<b>Priority:</b>	Normal	<b>Due date:</b>	08/29/2019
<b>Assignee:</b>		<b>% Done:</b>	100%
<b>Category:</b>		<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>		<b>Spent time:</b>	0.00 hour
<b>Description</b>			
Comprobar como esta el agarre del robot, en respecto al peso de la lata.			

#### History

#1 - 08/27/2019 10:29 AM - José Diaz

- % Done changed from 50 to 80

#2 - 08/31/2019 09:04 PM - José Diaz

- % Done changed from 80 to 100