

GRUPO 6 - Feature #5712

Feature # 5241 (In Progress): Control inalámbrico del robot

Cambio de programación del método de bloques a Python

11/07/2025 09:03 AM - Francisca Albornoz

Status:	Resolved	Start date:	10/27/2025
Priority:	Normal	Due date:	11/07/2025
Assignee:	Abraham Canaviri	% Done:	100%
Category:		Estimated time:	0.00 hour
Target version:		Spent time:	0.00 hour
Description			
Se comienza a usar un lenguaje de programación para la movilidad del robot de manera inalámbrica.			

History

#1 - 11/10/2025 08:38 AM - Francisca Albornoz

- Tracker changed from Bug to Feature

#2 - 11/12/2025 08:37 AM - Francisca Albornoz

- Status changed from New to Resolved

- % Done changed from 20 to 100

#3 - 11/12/2025 08:38 AM - Francisca Albornoz

- Due date set to 11/07/2025

- Start date changed from 11/07/2025 to 10/27/2025

#4 - 11/14/2025 08:17 AM - Francisca Albornoz

- Parent task set to #5241